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Functional adaptive control is a methodology applied for control of nonlinear dynamic systems that are not only sub- ject to uncertainty in the system parameters but also in the

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The field of intelligent control has recently emerged as a response to the challenge of controlling highly complex and uncertain nonlinear systems. It attempts to endow the controller with the key properties of adaptation, learning and autonomy. The field is still immature and there exists a wide

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A num ber of original neural network-based adaptive control designs are introduced for dealing with plants characterized by unknown functions, nonlinearity, multimodal behaviour, randomness and disturbances. The proposed schemes achieve high levels of performance by enhancing the controller's capability for adaptation, stabilization, management of uncertainty, and learning. Both

Functional Adaptive Model Estimation

Functional Adaptive Model Estimation GARETH M. JAMES and BERNARD W. SILVERMAN Abstract In

this article we are interested in modelling the relationship between a scalar, Y , and a functional

Control Lyapunov functions for adaptive nonlinear ...

The adaptive controller constructed in the proof of Theorem 2.1 consists of a control law $u = u(x, \theta)$ given by (2.4), and an update law $\dot{\theta} = Fz(x, \theta)$ with (2.11). It is of interest to interpret this controller as a certainty equivalence controller.