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With the Projection Equation it is even possible to describe multibody systems consisting of a combination of rigid and elastic bodies within the same framework. For further explanation see [2].

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The method is applied to rigid multibody systems where the rigid body is defined such that, by relaxation of the rigidity constraints, one can directly proceed to elastic bodies. A decomposition into subsystems leads to a minimal representation and to a recursive representation, respectively, of the equations of motion. Applied to elastic multibody systems one obtains, along with the use of [Dynamics of an elastic multibody chain: Part B Global dynamics](#)

[Dynamics and Stability of Systems Vol. 4 Nos. 3 & 4 1989](#)
[Dynamics of an elastic multibody chain: Part B-Global dynamics P. C. Hughes University of Toronto Institute for](#)

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