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Dynamics of Robots with Contact Tasks xi none of these conditions can be fulfilled. Therefore, the contact tasks are characterized by the dynamic interaction between the robot and environment, which often cannot be predicted accurately. The amount of mechanical work exchanged between the robot and environment during

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Dynamics of contact tasks in robotics. Part I: general ...

Contact problems in robot dynamics represent a very complex field of research. They relate to different areas of theoretical and applied mechanics, electromechanics, control theory etc. From the standpoint of mechanics one has to consider the issues of multibody dynamics, elasticity, friction and impact.

Adaptive control of multiple robots manipulation on a

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385 Adaptive control of multiple robots manipulation on a dynamical environment A I Tuneski1*, M K

Vukobratovic2 andG M Dimirovski3 1Faculty of Mechanical Engineering, Saints Cyril and Methodius University, Skopje, Republic of Macedonia

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Robot Dynamics and Control The dynamics of a robot manipulator describes how the robot moves in response to these actuator forces. For simplicity, we will assume that the actuators do not have dynamics A much harder control problem is one in which the robot is in contact with its environment. In this case, we must regulate not only the

Dynamics of Robots with Contact Tasks : M. Vukobratovic ...

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Mathematical model of multiple manipulators: cooperative ...

The problem addressed in this article is the synthesis of a mathematical model of multiple non-redundant rigid robot manipulators performing cooperative work on a single dynamical object the motion of which is constrained by a dynamical environment . So, the whole system consists of k non-redundant robots with rigid joints, a dynamical tool or

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