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For dynamical systems governed by feedback laws, time delays arise naturally in the feedback loop to represent effects due to communication, transmission, transportation or inertia effects.

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due largely to the current lack of effective methodology

for analysis and control design for such systems, the time-delay elements are often either neglected or poorly approximated, which

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Conference: Decision and Control, 1996., Proceedings of the 35th IEEE, Volume: 2 SP was originally presented for stable processes with dead time. It was then extended to unstable processes.

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Time delay is very often encountered in various technical systems, such as electric, pneumatic and hydraulic networks, chemical processes, long transmission lines, robotics, etc. The existence of pure time lag, regardless if it is present in the control or/and the state, may cause undesirable system transient response, or even instability. Consequently, the problem of controllability

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